

# Bouncing shells in Anti de Sitter space

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# Overview

- 1 Motivation
- 2 The problem
- 3 Results
- 4 Open questions

- Gravitational collapse process on  $AdS_{d+2} \sim$  thermalization of large  $N$ , large  $\lambda$   $CFT_d + 1$
- Look for model that allows explicit and straightforward calculations: thin shell spacetimes
- Usually considered in Poincare-AdS, mostly Vaidya spacetimes [Abajo-Arastia, Aparicio, Lopez; Valasubramaian, Bernamonti, de Boer, Copland, Craps, Keski-Vakkuri, Muller, Schafer, Shigemori, Staessens; Allais, Tonni; Keranen, Nishimura, Stricker, Taanila, Vuorinen and many more...]
- What happens if the field theory lives on a compact space?

What happens in global AdS?

- Global AdS-Vaidya describes direct black hole formation
- More general matter models lead to different behavior  
Example: massless scalar field
  - Localized scalar pulse can bounce back-and-forth between  $r = 0$  and  $r = \infty$  several times before collapsing [Bizon, Rostworowski]
  - There even exist exactly periodic solutions that never collapse [Maliborski, Rostworowski]
- Finite size systems may exhibit intrinsic quantum periodicity:  
bouncing  $\sim$  reviving + relaxation?

The question I will try to answer...

Can we find exactly periodic solutions in other matter models?

# The problem

- Simplifying assumption (i): *thin shell approximation*
- Simplifying assumption (ii):  $SO(d)$  symmetric thin shell
- Simplifying assumption (iii): perfect fluid shell

$$S_{ab} = \sigma u_a u_b + p (h_{ab} + u_a u_b)$$
$$p = \frac{\alpha}{d} \sigma$$

- Schwarzschild coordinates  $(t_{\pm}, r, \theta_1 \dots \theta_d)$  outside the shell
- Comoving coordinates  $(\tau, \theta_1 \dots \theta_d)$  on the shell worldvolume
- Line element

$$ds_{\pm}^2 = -f_{\pm}(r) dt_{\pm}^2 + f_{\pm}(r)^{-1} dr^2 + r^2 d\Omega_d^2$$
$$dh^2 = -d\tau^2 + r(\tau)^2 d\Omega_d^2$$

$$f_-(r) = 1 + r^2$$

$$f_+(r) = 1 + r^2 - \frac{m}{r^{d-1}}$$

How do we find the shell trajectory  $r(\tau)$ ? Israel junction conditions

$$\begin{aligned}[h_{ab}] &= 0 \\ [K_{ab}] &= -8\pi GS_{ab}\end{aligned}$$

### Shell equation of motion

$$\dot{r}(\tau)^2 + V(r(\tau)) = 0$$

$$V(r) = 1 + r^2 - \frac{1}{2}mr^{1-d} - \frac{m^2}{4M^2}r^{2\alpha} - \frac{1}{4}M^2r^{-2(d-1+\alpha)}$$

- Shell rest energy  $E = \sigma A = MA^{-d\alpha}$

# Looking for oscillating trajectories

- Asymptotics of  $V$ :  $V \rightarrow -\infty$  as  $r \rightarrow 0$ ;  $V \rightarrow \infty$  as  $r \rightarrow \infty$
- Oscillating shell trajectories are confined in an intermediate radial region bounded by two zeros of the potential, such that  $V < 0$  between them

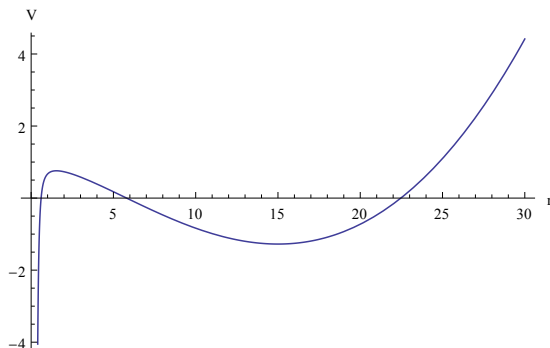


Figure: Example of potential well for  $d = 3$ ,  $\alpha = 0.99$ ,  $m = 0.5$ ,  $M = 0.2421$

- Fix  $d$ ,  $\alpha$  and  $m$ , oscillating shells iff  $M \in [M_l, M_u]$ 
  - $M = M_u$ , local minimum of  $V$  touching the  $V = 0$  axis (static shell)
  - $M = M_l$ , local maximum of  $V$  touching the  $V = 0$  axis (shell infalls below)

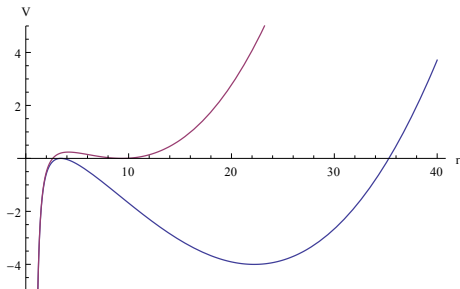


Figure: Potential for  $d = 3$ ,  $\alpha = 0.99$ ,  $m = 10$ ,  $M_u = 4.863$  -red- and  $M_l = 4.823$  -blue-



- We have to solve the system of equations

$$V(d, \alpha, m, M, r) = \partial_r V(d, \alpha, m, M, r) = 0$$

- The allowed M-region for oscillating solutions has an implicit analytic expression

$$\begin{aligned} r &= r(d, \alpha, m, M) \\ m &= \frac{4r^{d-1}(\alpha - (1 - \alpha)r^2)(d - 1 + \alpha + (d + \alpha)r^2)}{(d - 1 + 2\alpha)\sqrt{1 + r^2}} \\ M &= \frac{2r^{d-1+\alpha}(\alpha - (1 - \alpha)r^2)}{(d - 1 + 2\alpha)\sqrt{1 + r^2}} \end{aligned}$$

- As stated,  $M(d, \alpha, m)$  has two branches

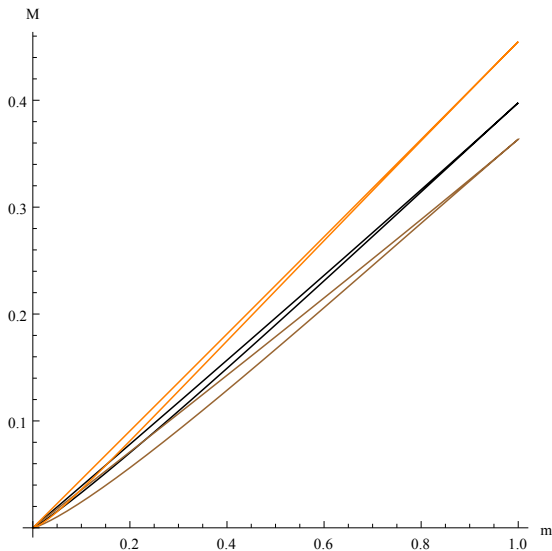


Figure:  $M(d, \alpha, m)$  for  $\alpha = 0.2, 0.5, 0.95$  in  $AdS_5$  -black, brown and orange curves respectively-. All quantities are measured in units of  $m_{max}(d, \alpha)$

# Some properties for $AdS_{d+2}$ , $d > 1$

- An oscillating shell never crosses its Schwarzschild radius  $r_h$
- There is always a maximum allowed mass  $m_{max}(d, \alpha)$  above which there are no oscillating solutions
- $m_{max}(d, \alpha)$  diverges as  $\alpha \rightarrow 1$

$$m_{max}(d, \alpha) \sim (1 - \alpha)^{\frac{1-d}{2}} + \dots$$

*We can have oscillating solutions of arbitrary mass as long as the shell matter is sufficiently near conformality*

- $m_{max}(d, \alpha)$  goes to zero as  $\alpha \rightarrow 0$

$$m_{max}(d, \alpha) \sim \alpha^{\frac{d+3}{2}}$$

*There are no pressureless oscillating solutions*

# $AdS_3$ is special

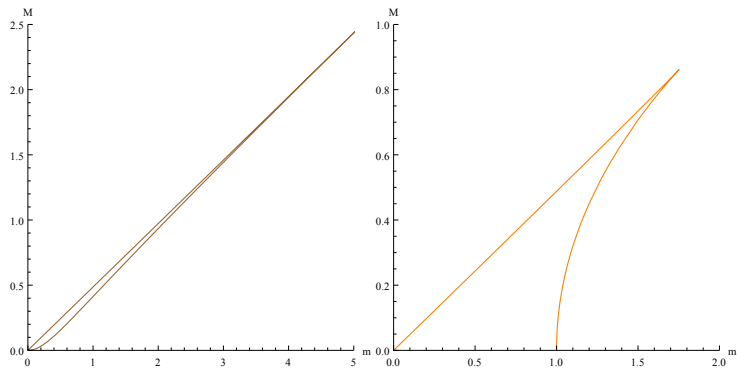


Figure: For  $\alpha = 0.99$ ,  $M(2, 0.99, m)$  -left, brown- versus  $M(1, 0.99, m)$  -right, orange-

- There are two different regimes separated by  $m = 1$
- $m > 1$ 
  - There are still two  $M$  branches; for  $M < M_l(\alpha, m)$  there are no oscillating solutions
  - There is still a maximal mass  $m_{max}(\alpha)$  that an oscillating solution can have

$$m_{max}(\alpha) = \frac{2}{1 + \sqrt{1 - \alpha^2}}$$

Again, *there are no oscillating pressureless solutions*

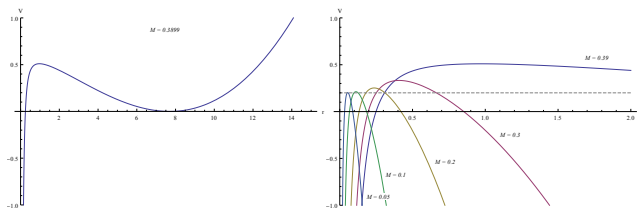
Now,  $m$  does not diverge as  $\alpha \rightarrow 1$ : *there is an absolute upper bound on the mass of an oscillating shell*

- $m < 1$ 
  - There is just one  $M$  branch; for  $M < M_u(\alpha, m)$  there are always oscillating solutions
  - These solutions are protected against forming naked singularities

# No naked singularities in $AdS_3$

- The potential barrier that keeps the shell away from  $r = 0$  approaches the origin, but it does not vanish at any finite  $m$

$$r_{\text{barrier}} \sim \left( \frac{M}{\sqrt{m}} \right)^{\frac{1}{\alpha}} \quad V_{\text{barrier}} \sim 1 - m$$



**Figure:** Left: for  $\alpha = 0.99$  and  $m = 0.8$ , potential  $V$  at  $M = 0.3899$ , which corresponds to a static shell located at  $r_u = 7.699$ . Right: evolution of the potential barrier for the bouncing shell at different  $M$

Several simplifying assumptions... is the model too simple?

- Do they still exist for other equations of state  $p = p(\sigma)$ ?
- Are these solutions stable?
  - Perturbatively: non spherical deformations and/or coupling to external fields...  
*These may lead to radiation emission by the shell, energy loss and eventual collapse to form a black hole*
  - Non-perturbatively: quantum tunneling  
*This effect should be relevant on a time scale parametrically larger than the one associated to perturbative effects*

Is the collapse time  $t_c$  that the shell needs to form a black hole larger than the period  $t_r$  of the shell?

Thanks for your time!