

Schematically $x(t, \alpha) = x(t, 0) + \delta x(t)$
 ↑
 Operator means variation by an arbitrary function!

Proof:

$$f(x(t, \alpha), \dot{x}(t, \alpha), t)$$

$$= f(x_0(t) + \delta x, \dot{x}_0(t) + (\delta \dot{x}), t)$$

Taylor expand:

$$\approx f(x_0(t), \dot{x}_0(t), t) + \frac{\partial f}{\partial x} \delta x + \frac{\partial f}{\partial \dot{x}} (\delta \dot{x})$$

$$\Rightarrow \delta J = \int_{t_1}^{t_2} \delta (f(x, \dot{x}, t)) dt$$

$$= \int_{t_1}^{t_2} \left(\frac{\partial f}{\partial x} \delta x + \frac{\partial f}{\partial \dot{x}} (\delta \dot{x}) \right) dt$$

but $\frac{d}{dt} \left(\frac{\partial f}{\partial \dot{x}} \delta x \right) = \frac{d}{dt} \left(\frac{\partial f}{\partial \dot{x}} \right) \delta x + \frac{\partial f}{\partial x} (\delta x)$

$$\Rightarrow \delta J = \int_{t_1}^{t_2} \left(\frac{\partial f}{\partial x} - \frac{d}{dt} \left(\frac{\partial f}{\partial \dot{x}} \right) \right) \delta x dt \quad \text{using } \delta x(t_1) = \delta x(t_2) = 0 \quad \triangle!$$

Exercise: Using that the distance along a curve $y(x)$ on a plane is given by

$$I[y(x)] = \int_{x_1}^{x_2} \sqrt{1 + \left(\frac{dy}{dx} \right)^2} dx$$

write the Euler-Lagrange equations which ~~must be obeyed~~ must be obeyed to minimize the distance between two points ~~$(x_1, y(x_1))$~~ $(x_1, y(x_1))$, $(x_2, y(x_2))$ and show that the solution is a straight line.

~~Hamiltonian formulation~~

→ This is all similar for many degrees of freedom:

$$q_a(t) \rightarrow q_a(t, 0) + \delta q_a$$

$$I[q_a(t)] \equiv \int_{t_1}^{t_2} L(q_a, \dot{q}_a, t) dt$$

$$\Rightarrow \delta I = \int_{t_1}^{t_2} \sum_a \left(\frac{\partial L}{\partial q_a} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_a} \right) \right) \delta q_a dt = 0$$

each = 0 \Rightarrow Euler-Lagrange equations.

Note: If $\frac{\partial L}{\partial q_a} = 0 \Rightarrow p_a \equiv \frac{\partial L}{\partial \dot{q}_a}$ is conserved!

(usual momentum if $q_a \rightarrow \vec{r}_a$
angular " if $q_a \rightarrow \theta, \phi, \dots$)

Advantages of Lagrangian formulation

- Generic coordinate systems (principle is independent of coordinates we use)

\Rightarrow symmetries are easier to deal with using appropriate coordinates (ex: angular momentum)

- In Field theory \Leftrightarrow many particle theory @ each space-time point

$$\Rightarrow \sum_a \rightarrow \int d^3x \quad \text{and}$$

We will get easily $\partial_\mu \left(\frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} \right) - \frac{\partial \mathcal{L}}{\partial \phi} = 0$
field

Hamiltonian formulation

General idea: $\left. \begin{matrix} \ddot{x}_a, \ddot{y}_a \\ x_a, y_a \end{matrix} \right\} \begin{matrix} \text{2nd order equations in} \\ \text{m-variables} \end{matrix}$

q_a ; $p_a \equiv \frac{\partial L}{\partial \dot{q}_a} \rightarrow$ conjugate momenta
2m-variables but first order equations

Achieved by a Legendre transformation:

$$H(q_a, p_a, t) \equiv \sum_a \dot{q}_a p_a - L$$

Note: \dot{q}_a needs to be eliminated for p_a

Then, the evolution equations are:

$$\rightarrow \begin{cases} \dot{q}_a = \frac{\partial H}{\partial p_a} \\ -\dot{p}_a = \frac{\partial H}{\partial q_a} \end{cases}$$

Exercise: Noting that $L(q_a, \dot{q}_a, p_a, t) = -H(q_a, p_a, t) + \sum_a \dot{q}_a p_a$ obtain the Hamiltonian equations above.

Note: If p 's are conservative

& $\vec{r}_i = (q_1, q_2, \dots, q_m)$ control

& T is at mass quadratic in \dot{q}_a

$\rightarrow H = T + V =$ total energy of the system when evaluated on the trajectory

Exercise: Solve the exercise for the shortest distance between two points on a plane, using the Hamiltonian formulation & constant.

Poisson Bracket formulation

Consider n generic functions $U(q_a, p_a, t)$
 $V(q_a, p_a, t)$

→ these will be observables

$$\text{define } \{U, V\}_{q,p} \equiv \frac{\partial U}{\partial q_a} \frac{\partial V}{\partial p_a} - \frac{\partial V}{\partial p_a} \frac{\partial U}{\partial q_a}$$

→ sum over repeated indices

This implies that $\{q_a, p_b\} = \delta_{ab}$

(In QM this will become $[q_a, p_b] = i\hbar \delta_{ab}$ Δ)

$$\mathcal{L} \Rightarrow \frac{dU}{dt} = \{U, H\} + \frac{\partial U}{\partial t}$$

→ particular cases, E.O.M. (obtained before)

$$\begin{cases} \dot{q}_a = \{q_a, H\} \\ \dot{p}_a = \{p_a, H\} \end{cases}$$

Ex: Check these give the Hamilton equations we had before

In QFT, quantisation of operators $\Rightarrow \{, \} \rightarrow \frac{1}{i\hbar} [,]$

4) Revision of Quantum Mechanics & the harmonic oscillator:

4.1) The postulates of Quantum Mechanics:

- Newtonian physics:

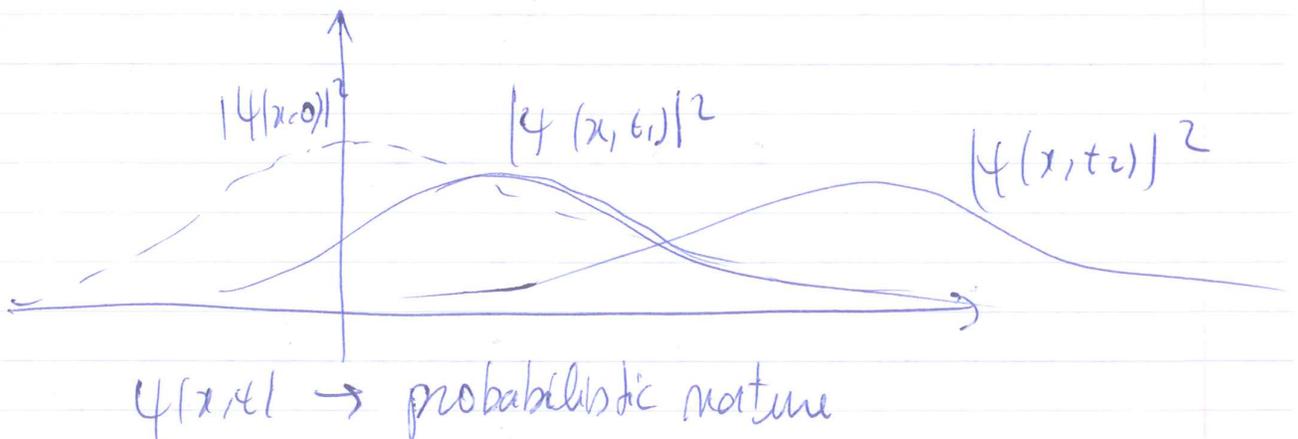
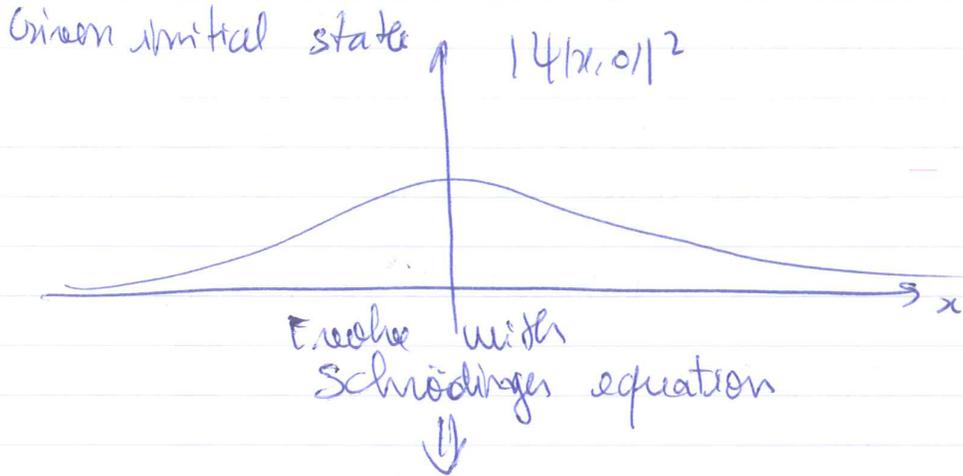
Given:

- $\vec{F}(x)$ & Eqn of motion

- Initial positions (x_0) and velocities (\dot{x}_0)

} \Rightarrow We know $x(t)$ for all times or any other observable
 (Ex: $p(t) = \dot{x}(t)$)

- In QM \rightarrow particles do not follow localized trajectories
 $\Delta x \Delta p \sim \hbar$



Postulates of Quantum Mechanics:

P₁: The state of a quantum system ^(m particles) is specified by a complex function $\psi(\vec{r}_1, \dots, \vec{r}_m, t)$, the wave function, which gives the probability

$dP(\vec{r}_1, \vec{r}_2, \dots, \vec{r}_m, t) = \psi^* \psi d\vec{r}_1 \dots d\vec{r}_m$, of finding the particles in the corresponding positions.

(Corollary: $\int dP = 1 \Rightarrow \int \psi^* \psi d\vec{r}_1 \dots d\vec{r}_m = 1$)

actually a vector on a Hilbert space which is square integrable

P₂: To every observable A in classical mechanics (H, \vec{p} , etc...) there exists a corresponding linear hermitian operator $\hat{A} = \hat{A}^\dagger$

Note: An operator A acts on ψ to give another normalizable complex wave function. The definition of adjoint is

such that $\int d\vec{r}_1 \dots d\vec{r}_m \chi^* \hat{A} \psi = \int d\vec{r}_1 \dots d\vec{r}_m (\psi^* \hat{A}^\dagger \chi)^*$

$$\begin{matrix} \chi(\vec{r}, t) \\ \psi(\vec{r}, t) \end{matrix} \left| \begin{matrix} \rightarrow \\ \rightarrow \end{matrix} \right.$$

Example: $H = T + V \xrightarrow{\text{Q.M.}} \hat{H} = \hat{T} + \hat{V} = \frac{\hat{p}^2}{2m} + V(\vec{r})$

$$p \rightarrow \hat{p} = -i \hbar \frac{\partial}{\partial x}$$

$$\Rightarrow \hat{H} = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x)$$

By definition $\hat{H} = \hat{H}^\dagger \Leftrightarrow \int \chi^* \hat{H} \psi = \int (\psi^* \hat{H}^\dagger \chi)^*$

Let us check if this is true... $\hat{H} = \hat{H}^\dagger$

$$\int \psi^* \hat{H} \psi$$

$$= \int \psi^* \left(-\frac{\hbar^2 \partial^2}{2m \partial x^2} + V(x) \right) \psi$$

Can we write this as $\int (\psi^* \hat{H}^\dagger \psi)$?

Let's integrate by parts:

$$\Rightarrow \frac{\partial}{\partial x} \left(-\psi^* \frac{\hbar^2 \partial \psi}{2m \partial x} \right) = -\psi^* \frac{\hbar^2 \partial^2 \psi}{2m \partial x^2} - \frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \partial \psi}{2m \partial x}$$

$$\Rightarrow \int dx \psi^* \left(-\frac{\hbar^2 \partial^2}{2m \partial x^2} \right) \psi$$

$$= \int dx \frac{\partial}{\partial x} \left(-\psi^* \frac{\hbar^2 \partial \psi}{2m \partial x} \right) + \int dx \frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \partial \psi}{2m \partial x}$$

$$= -\psi^* \frac{\hbar^2 \partial \psi}{2m \partial x} \Big|_{-\infty}^{+\infty} + \int dx \frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \partial \psi}{2m \partial x}$$

zero for square integrable functions

Let's integrate by parts again:

$$\frac{\partial}{\partial x} \left(\frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \psi}{2m} \right) = \frac{\partial^2 \psi^*}{\partial x^2} \frac{\hbar^2 \psi}{2m} + \frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \partial \psi}{2m \partial x}$$

$$\Rightarrow = \int dx \frac{\partial}{\partial x} \left(\frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \psi}{2m} \right) - \int dx \frac{\partial^2 \psi^*}{\partial x^2} \frac{\hbar^2 \psi}{2m}$$

$$= \frac{\partial \psi^*}{\partial x} \frac{\hbar^2 \psi}{2m} \Big|_{-\infty}^{+\infty} + \int dx \left(\psi^* \left(-\frac{\hbar^2 \partial^2}{2m \partial x^2} \right) \psi \right)$$

zero again

collecting we get (assuming $V(x)$ is real)

$$\int dx (\psi^* \underbrace{\left(-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x) \right) \psi}_{\text{by definition } \hat{H}^\dagger, \text{ but equal to } \hat{H}!})$$

$$\Rightarrow \hat{H}^\dagger = \hat{H}$$

→ Alternatively, this could have been just checked as in the lectures.

P3: In any measurement of an observable A , the only values that can be obtained are the eigenvalues $\{a\}$ of \hat{A} satisfying

$$\hat{A} \psi_a = a \psi_a$$

↘ ~~is~~ eigenfunction

Example: Free particle $\hat{H} = \hat{p}^2 = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2}$

$$\hat{H} \psi = E \psi \Leftrightarrow -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} = E \psi$$

Eigenfunction $\rightarrow \psi = e^{ikx} \Rightarrow \frac{\hbar^2 k^2}{2m} \psi = E \psi$

↘ Continuum energy spectrum.

P4: If the system (normalised) state is ψ and $\{a\}$ are the eigenvalues of \hat{A} , then the probability to observe a is

$$P(a) = \left| \int_{\text{all space}} \psi_a^* \psi dx \right|^2$$

P5 (Collapse of the wave function): As a result of a measurement of observable \hat{A} , in which the value a is obtained, the state of the system becomes ψ_a

$$\psi \rightarrow \psi_a$$

P6 (Evolution): Between measurements, the wave function evolves according to the time dependent Schrödinger equation:

$$i\hbar \frac{\partial \psi}{\partial t} = \hat{H} \psi, \quad \hat{H} \text{ is the Hamiltonian of the system}$$