

Exercises – Special Relativity Revision

Marco Sampaio – msampaio@ua.pt

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1 Pre-Relativity

1. Consider a transformation of coordinates obtained by a constant translation with a Galileo transformation (i.e. the most general transformation leaving Newton's equations invariant without rotations). Show that the composition of two such transformations is a transformation of the same type. Identify the translation and velocity of the composed transformation.
2. (Lecture exercise) Consider two particles with position vectors \vec{r}_p and \vec{r}_q interacting through a general force of the type

$$\vec{F}_p = -\vec{F}_q(|\vec{r}_p - \vec{r}_q|, |\vec{v}_p - \vec{v}_q|)$$

Show that applying a general transformation as in Ex.1, or a rotation to each particle, then

$$R.\vec{F}_{p/q}(|\vec{r}'_p - \vec{r}'_q|, |\vec{v}'_p - \vec{v}'_q|) \equiv \vec{F}'_{p/q} = m_{p/q} \frac{d^2 \vec{r}'}{dt'^2}$$

3. Consider the group of rotations in 3D:
 - (a) Show that the product of two rotation matrices is still a rotation matrix, using the two defining conditions (hint: the second condition excludes reflections).
 - (b) Consider the following vectors and matrices in index notation:

$$V^i \rightarrow \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \quad W_i \rightarrow (0, 0, -5) \quad M_{ij} \rightarrow \begin{pmatrix} -2 & 7 & 2 \\ 0 & 0 & 3 \\ 4 & -5 & 0 \end{pmatrix}$$

Compute $V^i W_i$ (what can you say about the result), $V^i M_{ij}$ and $M_{ij} V^i$.

- (c) Repeat the proof of the first condition in part (a) using index notation.
- (d) Write a rotation matrix corresponding to a rotation around the z axis and identify the rotation angle.
- (e) Compute the composition of two rotation matrices of the type in (d) and show explicitly what the angle corresponding to the composed rotation is.

2 Lorentz transformations & Minkowski space

1. Consider the group of Lorentz transformations.

- (a) Show, first in matrix notation, that the composition of two Lorentz transformations is still a Lorentz transformation. Repeat the proof using index notation.
- (b) (Index notation) Given the following:

$$A^\alpha \rightarrow \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ 3 \\ -9 \end{pmatrix} \quad B_\alpha \rightarrow (5, -2, -1, -7) \quad C_{\alpha\beta} \begin{pmatrix} 1 & 3 & 6 & -1 \\ 0.1 & 8 & 4 & 2 \\ 0 & 0 & 0.3 & -3 \\ 1 & 0 & 0 & 1 \end{pmatrix}$$

Compute A_α , B^α , C^α_β , C^β_α , $C^{\alpha\beta}$, $A^\alpha B_\alpha$ and $C_{\alpha\beta} A^\beta$.

- (c) (Lecture Exercise) Using the definition of Lorentz transformations $\Lambda^T \eta \Lambda = \eta$, show that the most general transformation Λ involving t, x (i.e. y, z not transformed) is

$$\Lambda = \begin{pmatrix} \cosh \phi & -\sinh \phi & 0 & 0 \\ -\sinh \phi & \cosh \phi & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \phi \in \mathbb{R}$$

which implies

$$\begin{aligned} x^{0'} &= ct' = \cosh \phi ct - \sinh \phi x \\ x^{1'} &= x' = -\sinh \phi ct + \cosh \phi x \\ x^{2'} &= y' = y \\ x^{3'} &= z' = z \end{aligned}$$

Also show that the velocity of the origin of the moving frame O' defined by being at rest in O' (i.e. $x' = 0$) moves with velocity $v \equiv c \tanh \phi = \tanh \phi$ ($c = 1$), so that we can write

$$\Lambda = \begin{pmatrix} \gamma & -\gamma v & 0 & 0 \\ -\gamma v & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \gamma \equiv \frac{1}{\sqrt{1-v^2}}$$

- (d) Using the parametrization of a Lorentz transformation on the plane xt (called Lorentz boost), write the transformation with a pseudo-angle ϕ .
- (e) (Lecture exercise) Write the composition of two transformations in (c) for two different pseudo-angles and identify:
- The pseudo-angle of the composed transformation.
 - The velocity of each transformation and the velocity of the composed transformation in terms of the first two.
 - Compare the result with that composition of two Galileo transformations and comment.
 - Recover the Galileo transformation by taking the small velocity limit.

- (f) Write a Lorentz transformation corresponding to a rotation around the z axis.
- Compute the composition of such rotation with a Lorentz boost on the xt plane.
 - Compute the composition in reversed order.
 - Comment the results of (i) and (ii).
- (g) Consider a Lorentz transformation on x, t :
- Compute the inverse transformation.
 - Show that the inverse of (i) is still a Lorentz transformation.
 - Consider a general Lorentz matrix and its (formally defined) inverse. Show that the inverse is still a Lorentz transformation (i.e. it still obeys the orthogonality relation with respect to $\eta_{\mu\nu}$ and the determinant condition).
2. Show that the sum of two future directed timelike vectors is still a future directed timelike vector.
3. Consider a space-time diagram $x^0 x^1(t-x)$ in an inertial frame \mathcal{O} . Represent in such diagram:
- The trajectory of an observer at rest at $x^1 = 1m$
 - The trajectory of a particle moving with a velocity $v = 0.1c = 0.1$, such that when $x^0 = ct = 0m$, the particle goes through $x^1 = 5m$.
 - The axis $x^0 x^1$ of an observer \mathcal{O}' moving with speed $v = 0.5$ along the x^1 axis relative to \mathcal{O} and with the same origin.
 - Consider a generic vector r^μ in such diagram, connecting the origin to an event P :
 - Represent the points in the diagram corresponding to events separated by a proper time to the origin $r^\mu r_\mu = -(1m)^2$
 - Represent the points in the diagram corresponding to events separated by a proper space-like distance to the origin $r^\mu r_\mu = (1m)^2$
 - the location of events which are simultaneous for \mathcal{O} at the time $x^0 = 2m$
 - the location of events which are simultaneous for \mathcal{O}' when $x^{0'} = 2m$
 - the trajectory of a photon which is emitted at $x^0 = -1m$ and $x^1 = 0m$, travels in the negative x^1 direction, is then reflected back in a mirror when arrives at $x^1 = -1m$ so it then travels in the positive x^1 direction and gets absorbed at $x^1 = 0.75m$.
4. (Lecture Exercise) Time dilation: Consider 2 events $P^\mu \rightarrow (0, 0, 0, 0)$ and $Q^\mu \rightarrow (T, 0, 0, 0)$. Represent them in a spacetime diagram, and show that their time separation in a moving frame \mathcal{O}' is

$$T' = \gamma T \equiv \frac{1}{\sqrt{1-v^2}} T$$

5. (Lecture Exercise) Space contraction: Consider a rod of length d at rest with endpoints following world lines $P^\mu \rightarrow (t, 0, 0, 0)$ and $Q^\mu \rightarrow (t, d, 0, 0)$. Represent the world lines of the endpoints in a spacetime diagram, and show that the length of the rod seen in a moving frame \mathcal{O}' is $d' = \sqrt{1-v^2}d$.